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| **Mission 2: Python with Robotics**  **Check for Understanding** | **Name:** |
| Label the parts of the CodeBot. Indicate if they are used for input or output. | |
|  | |
| **1.** | **9.** |
| **2.** | **10.** |
| **3.** | **11.** |
| **4.** | **12.** |
| **5.** | **13.** |
| **6.** | **14.** |
| **7.** | **15.** |
| **8.** | **16.** |

Parts of CodeBot:

* Accelerometer
* Expansion connector
* Battery pack
* User LEDs
* Wheel encoders
* Line sensor LEDs
* Line sensors
* Button 0
* Button 1
* Wheels
* USB connector
* Proximity sensors
* Reboot button
* Speaker
* Motors
* Power switch